

## 4-20mA, 0-10V Analog Front-End to Digital through I2C bus on Small Board



#### 1. Features

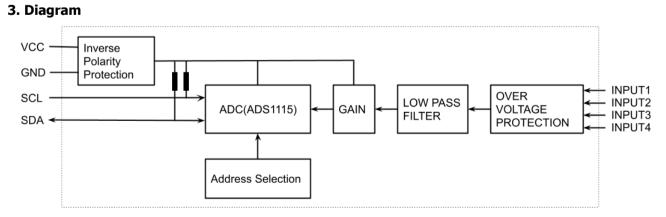
- 4 Channels of analog inputs
- Voltage on each input: 0-5V, 0-10V
- Current on each input: 0-20mA, 4-20mA, 0-40mA, 0-80mA
- 16-bit ADC, ADS1115
- I2C bus speed 100Khz, 400Khz, 3.4Mhz
- Availability pull-up resistors on I2C lines
- Up to 4 boards on a single bus
- A single supply voltage: 2.7V to 5.5V for operation
- Inverse polarity protection circuits for power supply
- Over voltage protections for inputs
- Lowpass Filter
- Programable digital filter
- Programable data rate

#### 2. Introduction

This is an I2C bus analog to digital converter board, small I2C ADC board. Voltage and current sources can be connected to each input of the board. The board converts the analog value to digital value then the digital value can be processed by microcontrollers. The microcontrollers can read the digital values through I2C bus. The small I2C ADC board has four inputs. Each input accepts voltage 0-5V and 0-10V and current 0-20mA, 4-20mA, 0-40mA and 0-80mA. Resolution of digital value of the board is 16 bits which the most significant bit (MSB) is used for a sign bit.

The board needs only a single supply voltage from 2.7V to 5.5V. The I2C bus is compatible with the standard 100Khz, 400Khz and 3.4Mhz modes.

The I2C bus addresses are selected by jumpers. The board can be configured to one of four addresses. It means four boards can be connected on a single bus. The board has two 10K ohm pull-up resistors for I2C lines, SCL and SDA lines. The users can enable or disable them with the jumpers.



#### Figure 1: Diagram



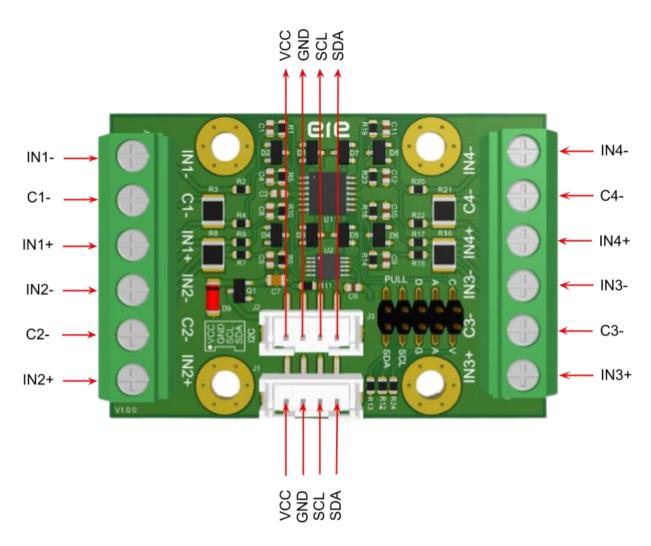


Figure 2: Board Layout

Table 1: Signal Descriptions

Symbol	Descriptions				
VCC	A single power supply voltage.				
GND	Ground.				
SCL	I2C bus, serial clock signal.				
SDA	I2C bus, serial data signal.				
PULL (SDA)	A jumper for selecting a 10K pull-up resistor on the SDA line.				
PULL (SCL)	A jumper for selecting a 10K pull-up resistor on the SCL line.				
A (jumper)	An address pin of ADS1115.				
V (jumper)	A VCC signal pin. The address pin can connect to this pin for selecting one of four different addresses.				
G (jumper)	A GND signal pin. The address pin can connect to this pin for selecting one of four different addresses.				



C (jumper)	A SCL signal pin. The address pin can connect to this pin for selecting one of four different addresses.
D (jumper)	An SDA signal pin. The address pin can connect to this pin for selecting one of four different addresses.
IN1+ IN4+	Positive voltage and positive current for INPUT1 to INPUT4. The positive current means that the current flows into the board.
IN1 IN4-	Negative voltage for INPUT1 to INPUT4
C1 C4-	Negative current for INPUT1 to INPUT4 (connect to IN1 IN4- when an input is current). The negative current means that the flows out from the board.

#### 4. Analog Inputs

Voltage and current sources can be connected to inputs of the board. The voltage of each channel can be 0-5V and 0-10V. Also, the current of each channel can be 0-20mA, 4-20mA, 0-40mA and 0-80mA.

#### 5. Voltage and Current Connection

When a voltage source connects to the board. The positive and the negative poles of the voltage source must connect to the INx+ and INx- pins of the board respectively while the Cx- pin is non-connect.

While a current source connects to the board. The output wire of the current source must connect to the INx+ pin, and the positive wire of the current source must connect to a positive pole of a power supply. The INx- and Cx- must be shorted together and connected to the negative pole of the power supply.

The power supply (Vs) must have enough voltage for a sensor to operate because the voltage, 1.24V will drop across the input pins of the board when current, 20mA flows through a loop. An example if a sensor needs 9V at least for operation. The power supply (Vs) must have 10.24V at least.

x means channel number 1,2,3 and 4

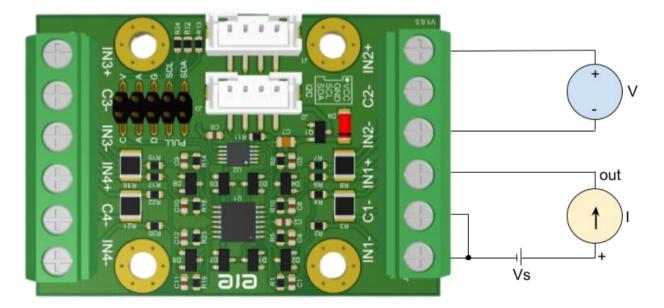


Figure 3: Input Connection

Input Sources	Full Scale Range (FSR)	Front-End Gain (FEG)	Input Full Scale	Max. code
0 - 5 V	1.024 V	0.2	5.120 V	32767
0 - 10 V	2.048 V	0.2	10.240 V	32767
0 - 20 mA	0.256 V	0.2	20.645 mA	32767
4 - 20 mA	0.256 V	0.2	20.645 mA	32767
0 - 40 mA	0.512 V	0.2	41.290 mA	32767
0 - 80 mA	1.024 V	0.2	82.258 mA	32767

MSB bit of the digital code is a sign bit. For this board, the sign bit (MSB) is away zero, it represents positive value.

**Full Scale Range (FSR)** is the full-scale input voltage range of the ADS1115. Setting this value through I2C bus.

**Front-End Gain (FEG)** is a gain of front-end op-amp circuit of each channel. The Front-End Gain (FEG) of the board is  $\frac{36}{180}$  or 0.2.

**Input Full Scale** is the maximum value of input signal when digital code is maximum. This value can be calculated by

**Input Full Scale** =  $\left(\frac{FSR}{FEG}\right)$ 

The input voltage can be calculated from a digital code that reads through the I2C bus.

**Input Voltage** =  $\left(\frac{code}{Max\_code}\right)\left(\frac{FSR}{FEG}\right)$ 

Also, if the input signal is current. The value of the current can be calculated.

**Input Current** =  $\frac{Input\_Voltage}{62}$ 

#### 6. I2C Bus pull-up Registers

The I2C bus needs resistors for pulling-up SCL and SDA lines. The board has two 10K ohm resistors for this purpose. These resistors can be enabled by closing jumpers. These resistors must be enabled if there is not any resistor on the I2C bus.

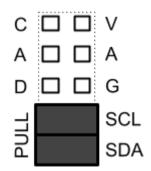


Figure 4: Enable PULL-UP resistors.

The bus usually needs only a pair of resistors when boards are connected on a single bus. More pairs of resistors on a single bus make the bus very strong. But a strong bus is needed for high frequency of clock signal. The 10K ohm is suitable for 100KHz bus frequency.



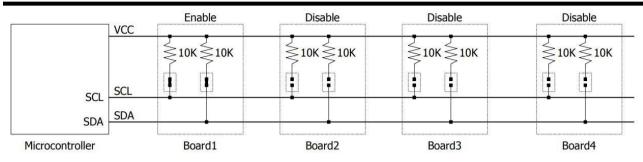


Figure 5: I2C bus pull-up resisters

#### 7. Interfacing

The VCC must be supplied from a microcontroller board. The SCL and SDA pins of the boards must be connected to SCL and SDA pins of microcontroller respectively. Remember pull-up resistors must be enabled when there is no external pull-up resistor on the bus. The boards can be connected to 4 boards on a single bus.

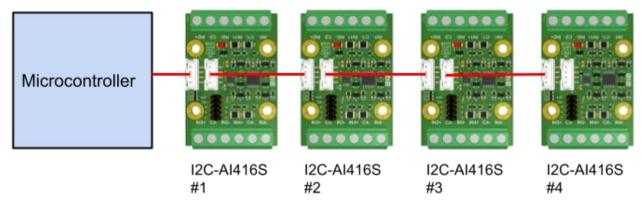


Figure 6: Multiple boards on a single bus

#### 8. Address

The board is addressed by jumpers to make 4 different addresses.

Table 3: Address Setting

7-BIT I2C ADDRESSES	ADDR PIN CONNECTS TO	JUMPER SETTING
1001000 (48H)	GND	C C C V A C A G C C C C C C C C C C C C C C C C C C C
1001001 (49H)	VCC	C C A A A A C G G C C C C C C C C C C C
1001010 (4AH)	SDA	C C C A A A D G C C A C C A C C C C C C C C C C C C C C
1001011 (4BH)	SCL	C A A A D G G J C SCL

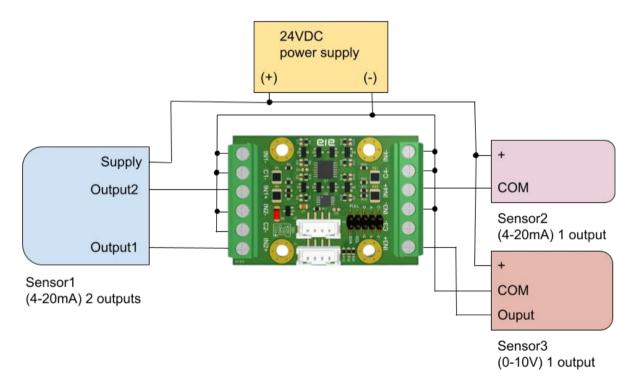
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Table 4: Specification

Operating voltage	2.7V – 5.5V
Interface	I2C bus
Boards on a single bus (max.)	4 boards
I2C bus frequency	100Khz, 400Khz, 3.4Mhz
Input channels	4 channels
ADC resolution	16-bit (MSB bit is a sign bit)
Input voltage ranges	0-5V, 0-10V
Input current ranges	4-20mA, 0-20mA, 0-40mA, 0-80mA
Input voltage drop @20mA	1.24V
Input current loop resistance	62 ohms
Filter	Lowpass Filter
Input over voltage protection (max.)	30V

#### 9. Application



#### Figure 6: Sensors are connecting to a board.



#### **10.** Dimensions

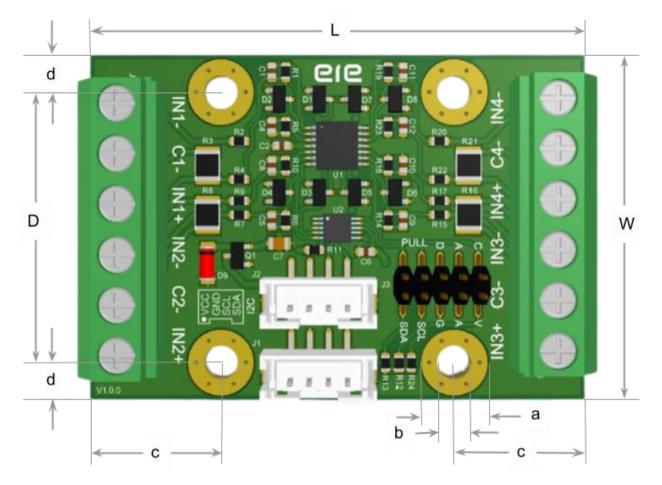


Figure 7: Board Dimensions

Table 5: Board Dimensions

	L	w	D	а	b	с	d
inch	2.086	1.456	1.141	0.279	0.141	0.551	0.157
mm	53.00	37.00	29.00	7.10	3.60	14.00	4.00

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